

# **New Integrated Servo Motor iSV-\*\*\*T Series**

### BLDC Servo Integrated Motor, 24-50VDC, Frame 57mm, 90W-180W

Leadshine's iSV-\*\*T integrated servo motor is a 57mm frame size brushless motor integrated with a 16bit encoder and a servo drive. At very compact size and with all components integrated, the iSVxxx-T can save mounting space, eliminate encoder connection & motor wiring time, reduce interference, and cut/reduce cable and labor costs.

- Step & direction command input for position control
- Compatible mounting size with 57mm stepper motor
- Smooth motor movement and excellent respond time
- Isolated control inputs of Pulse, Direction
- Easy to tuning for CNC application
- Low torque-ripple with new design of magnetic circuit



| Part Number        | ISV-B23090T-D4 | ISV-B23130T-D4 | ISV-B23180T-D4 |
|--------------------|----------------|----------------|----------------|
| Rated Power(W)     | 90             | 130            | 180            |
| Rated Torque(Nm)   | 0.3            | 0.45           | 0.6            |
| Peak Torque(Nm)    | 0.9            | 0.9            | 0.9            |
| Rated Speed(rpm)   | 3000           | 3000           | 3000           |
| PeakSpeed(rpm)     | 4000           | 4000           | 4000           |
| Rated Voltage(Vdc) | 36             | 36             | 36             |
| Weight(kg)         | 0.95           | 1.25           | 1.54           |

| Parameter                    | Min | Typical | Max | Unit      |
|------------------------------|-----|---------|-----|-----------|
| Input Voltage                | 20  | 36      | 50  | VDC       |
| <b>Continuous Current</b>    | 0   | -       | 6.0 | A         |
| <b>Pulse Input Frequency</b> | 0   | -       | 200 | kHz       |
| Pulse Voltage                | 0   | 5       | 24  | V         |
| Logic Signal Current         | 7   | 10      | 16  | mA        |
| <b>Isolation Resistance</b>  | 100 | -       | -   | $M\Omega$ |

# Connectors and Pin Assignment

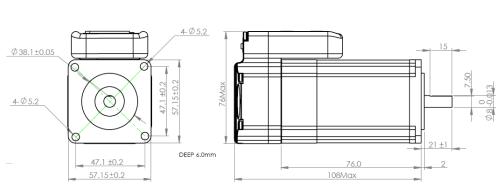
| Power Connector |      |     |  |
|-----------------|------|-----|--|
| Pin             | Name | I/O | Description  |
| 1               | +Vdc | I   | Power Supply Input (Positive)24-40VDC recommended. Please leave reasonable reservation for voltage fluctuation and back-EMF during deceleration. |
| 2               | GND  | GND | Power Ground (Negative)  |

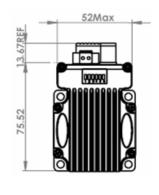
| RS232 Communication Connector |      |     |  |  |
|-------------------------------|------|-----|--|--|
| Pin                           | Name | I/O | Description  |  |
| 1                             | +5V  | O   | +5V power output (Note: Do not connect it to PC's serial port) |  |
| 2                             | TxD  | O   | RS232 transmit.  |  |
| 3                             | GND  | GND | Ground.  |  |
| 4                             | RxD  | I   | RS232 receive.   |  |
| 5                             | NC   | -   | Not connected.   |  |



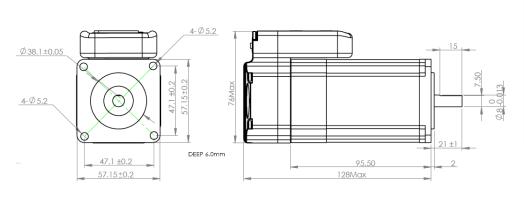
|     | Control Signal Connector |     |   |  |  |  |
|-----|--------------------------|-----|---|--|--|--|
| Pin | Name                     | I/O | Description   |  |  |  |
| 1   | PUL+                     | I   | <u>Pulse Signal</u> : In single pulse (pulse/direction) mode, this input represents pulse signal, active at each rising or falling edge (Software configurable). In double pulse mode (software configurable), this input represents clockwise (CW) pulse, active both at each high level and | The fuction of four pins will be   |  |  |
| 2   | PUL-                     | I   | low level. 4.5-24V for PUL-HIGH, 0-0.5V for PUL-LOW. For reliable response, pulse width should be longer than $2.5\mu s$ for 200K MAX input frequency or $1\mu s$ for 500K MAX input frequency.   | different if ISV motor works in internal velocity mode.                                  |  |  |
| 3   | DIR+                     | I   | <u>Direction Signal</u> : In single-pulse mode, this signal has low/high voltage levels, representing two directions of motor rotation. In double-pulse mode (software configurable), this signal is counter-clock (CCW) pulse, active both at high level and low level. For reliable motion  | Pls refer to chapter 3 and chapter 4 about how to use these four pins for velocity mode. |  |  |
| 4   | DIR-                     | I   | response, DIR signal should be ahead of PUL signal by 5µs at least. 4.5-24V for DIR-HIGH, 0-0.5V for DIR-LOW. Toggle DIP switch SW5 to reverse motion direction.  |  |  |  |
| 5   | ALM+                     | О   | <u>Alarm Signal</u> : OC output signal, activated when one of the following protection is activated: over-voltage and over current error. They can sink or source MAX 50mA current at 24V. By default, the impedance between ALM+ and ALM- is low for normal operation and becomes            |  |  |  |
| 6   | ALM-                     | О   | high when any protection is activated. The active impedance of alarm signal is software configurable.   |  |  |  |

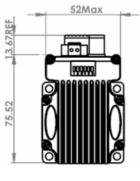
# Mechanical Specifications





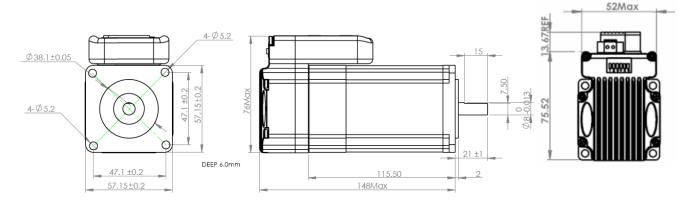
Mechanical Specification of iSV-B23090T-D4





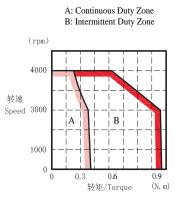
Mechanical Specification of iSV-B23130T-D4

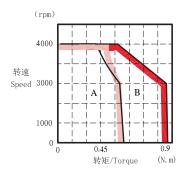


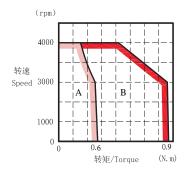


Mechanical Specification of iSV-B23180T-D4

## Curve of Torque-speed





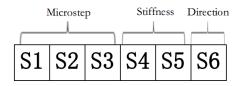


iSV-B23090T-D4

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iSV-B23180T-D4

# DIP Switch Settings



### . Pulses/Rev (S1-S3)

| Pulse/rev | S1  | <b>S2</b> | <b>S3</b> |
|-----------|-----|-----------|-----------|
| Pr0.08    | Off | Off       | Off       |
| 1600      | On  | Off       | Off       |
| 2000      | Off | On        | Off       |
| 3200      | On  | On        | Off       |
| 4000      | Off | Off       | On        |
| 5000      | On  | Off       | On        |
| 6400      | Off | On        | On        |
| 8000      | On  | On        | On        |

### Stiffness setting(S4—S5)

| ,         |           |           |
|-----------|-----------|-----------|
| Stiffness | <b>S4</b> | <b>S5</b> |
| Pr0.03    | Off       | Off       |
| 9         | On        | Off       |
| 10        | Off       | On        |
| 11        | On        | On        |



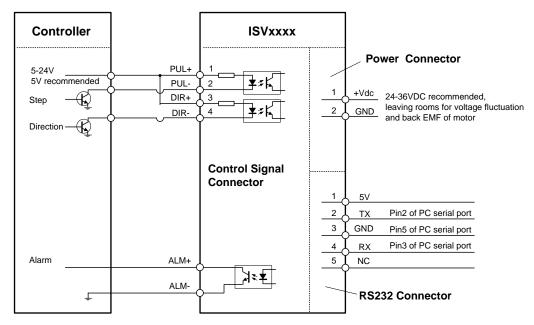
#### Motor Shaft Direction (S6)

DIP switch S6 is used for changing motor shaft rotation direction. Changing position from "ON" to "OFF", or "OFF" to "ON" will reverse iSVxxx rotation direction.

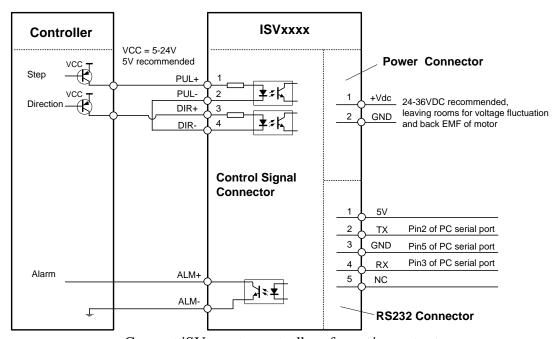
| <b>S6</b> | Direction |
|-----------|-----------|
| Off       | CCW       |
| On        | CW        |

#### RS232 Communication Cable Connections

**Note1:** The RS232 communication port is not isolated. Please use an isolated power supply for the ISVxxx when the PC's serial port is not isolated.

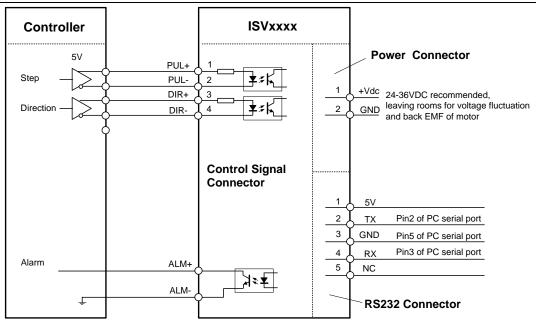


Connect iSV-xxx to controller of sinking output



Connect iSV-xxx to controller of sourcing output





Connect iSV-xxx to controller of differential output